



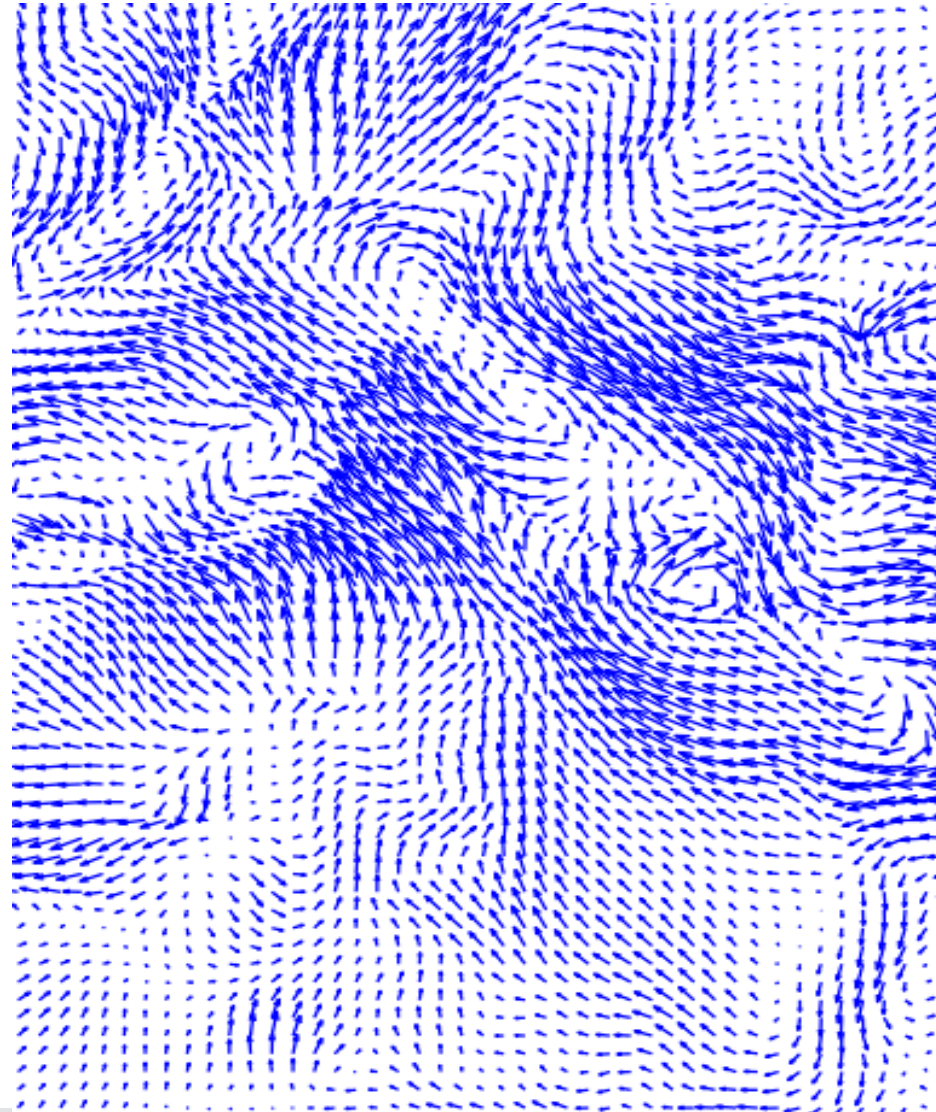
*Photo: A. Christen*

## 18 Turbulence - statistically approached.

# Today's learning objective

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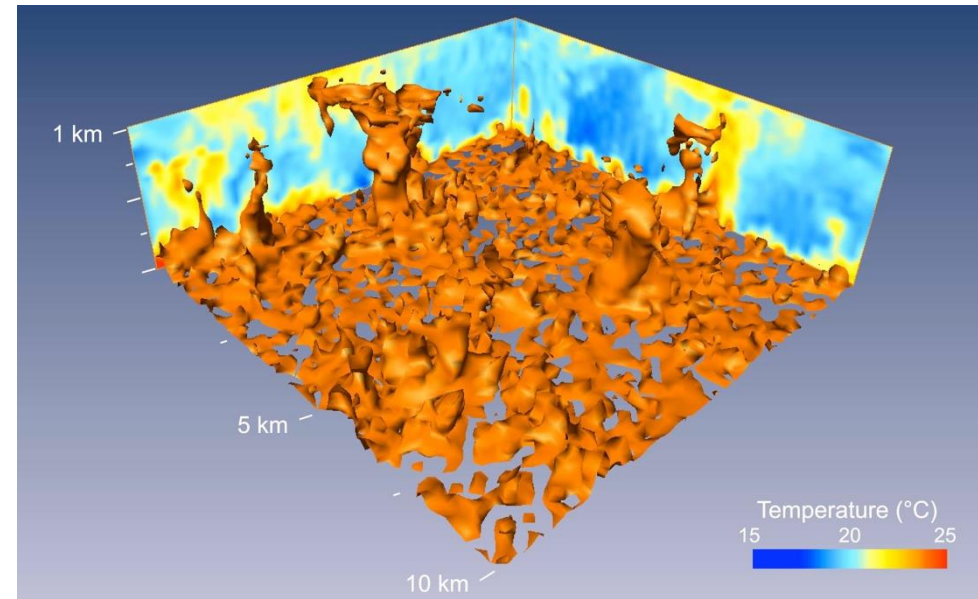
- Describe how we can separate turbulent from mean kinetic energy.
- Explain how we can quantify turbulence and its properties.



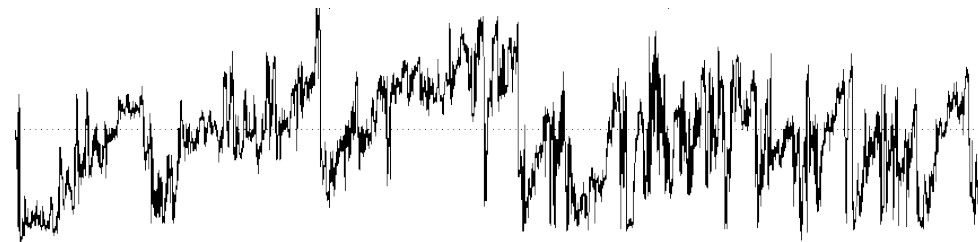
## Statistical approach.

Single motions in a turbulent flow are chaotic and unpredictable. Luckily, they are seldom of importance, and any prediction focuses on resulting integral effects of turbulence on dispersion and exchange processes.

- **Where** are regions of strong / weak turbulence?
- **When** is the flow more / less turbulent?
- How **efficiently** does turbulence transfer energy and mass?



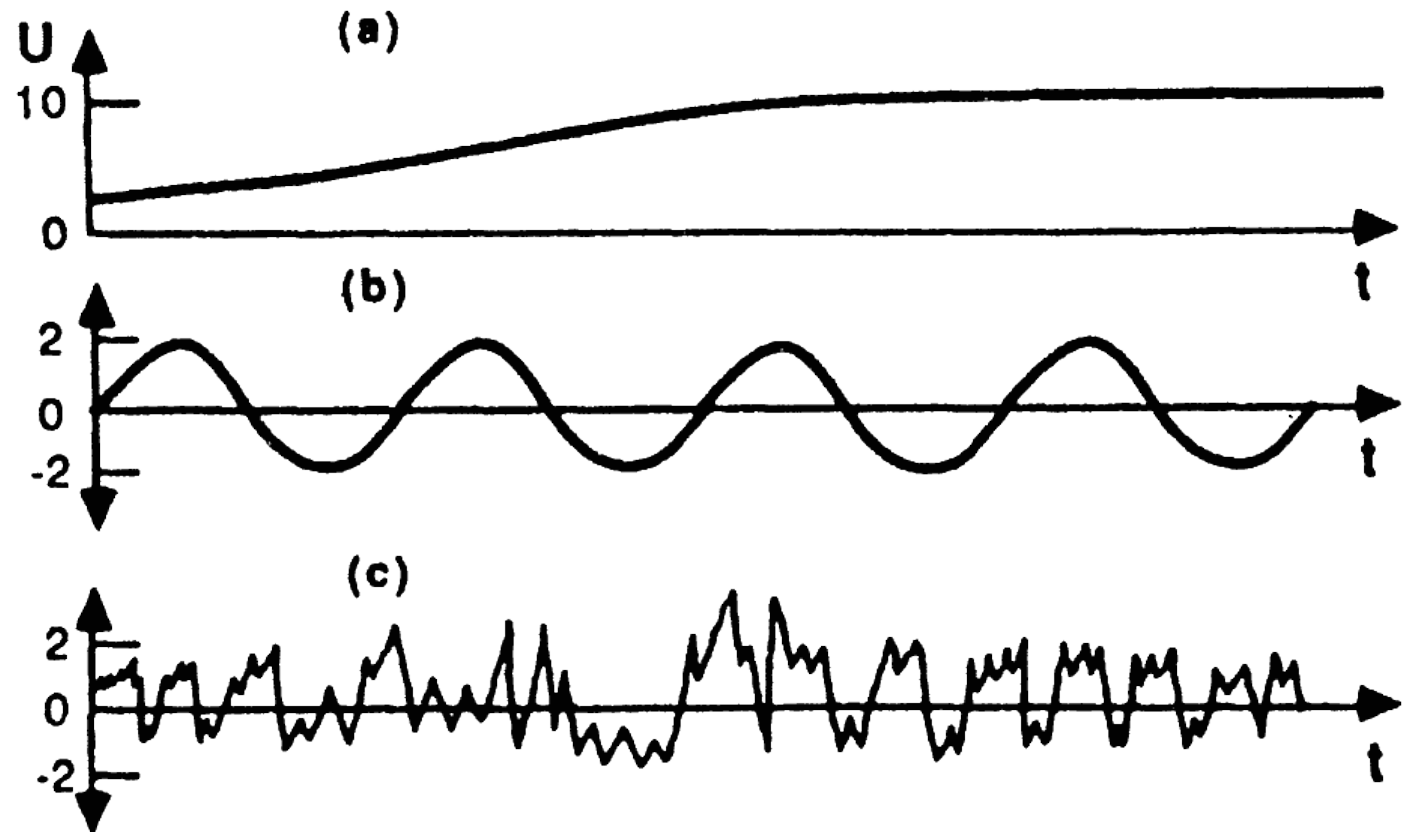
Sample instantaneous situation of a temperature field in a Large Eddy Simulation of the PBL (M. A. Carper, Saint Anthony Falls Laboratory, University of Minnesota)



Sample turbulent time series of measured temperatures (10 min).

## Mean flow – waves – turbulence.

**Fig. 1.3**  
Idealization of  
(a) Mean wind  
alone, (b) waves  
alone, and (c)  
turbulence alone.  
In reality waves  
or turbulence are  
often super-  
imposed on a  
mean wind.  $U$  is  
the component  
of wind in the  
 $x$ -direction.

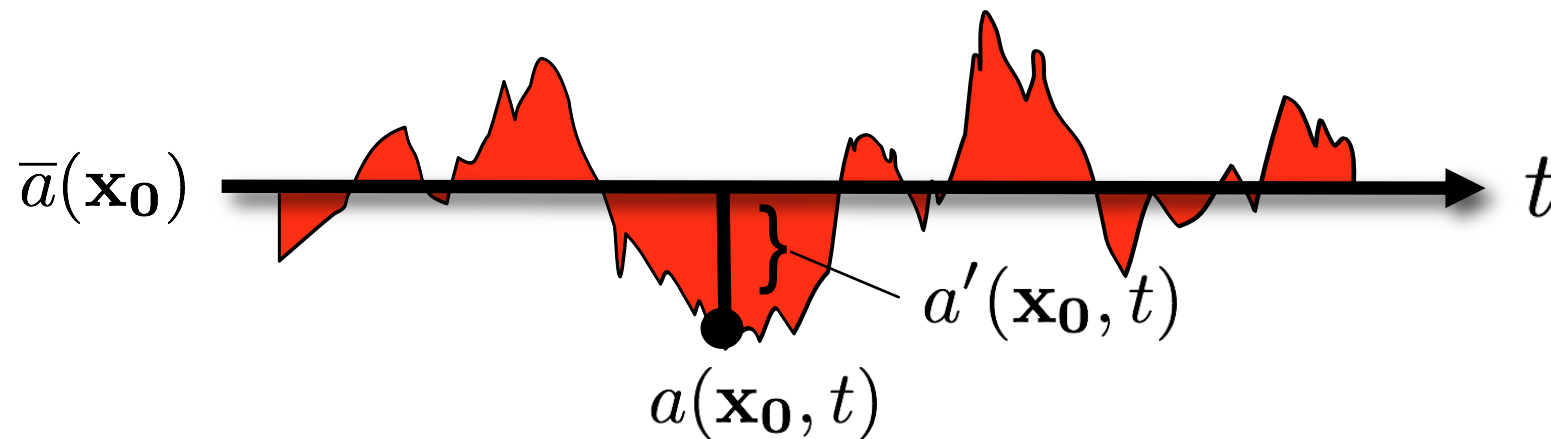


R. B. Stull (1988): 'An introduction to boundary layer meteorology', Kluwer Academic Publishers.

# Reynolds decomposition

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The Reynolds decomposition separates a time series measured at one point  $\mathbf{x}_0$  into a mean and a turbulent part:

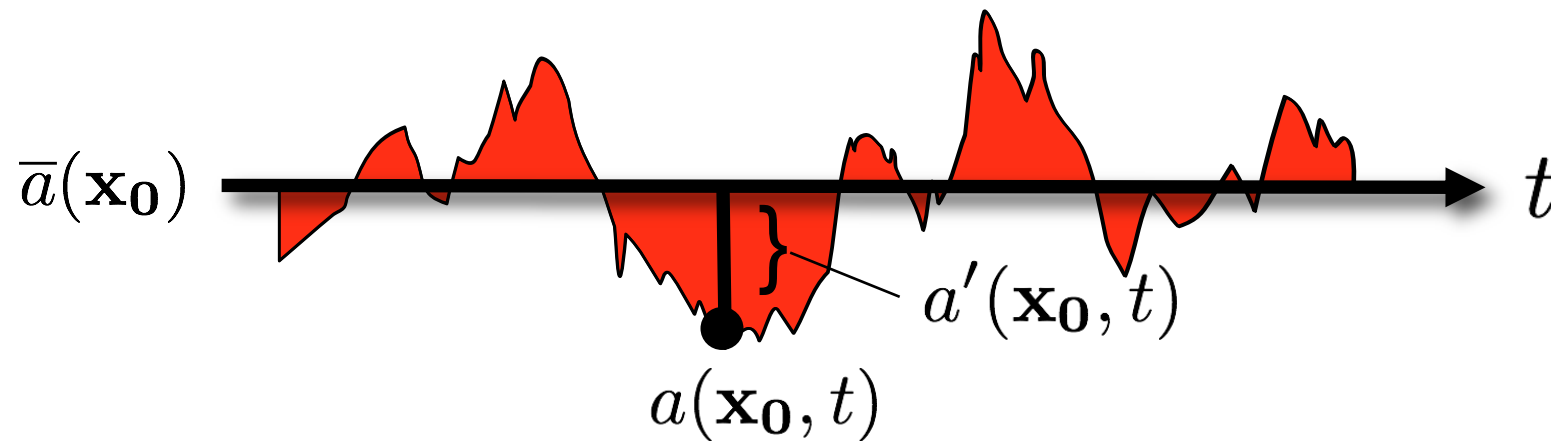


# The averaging operator

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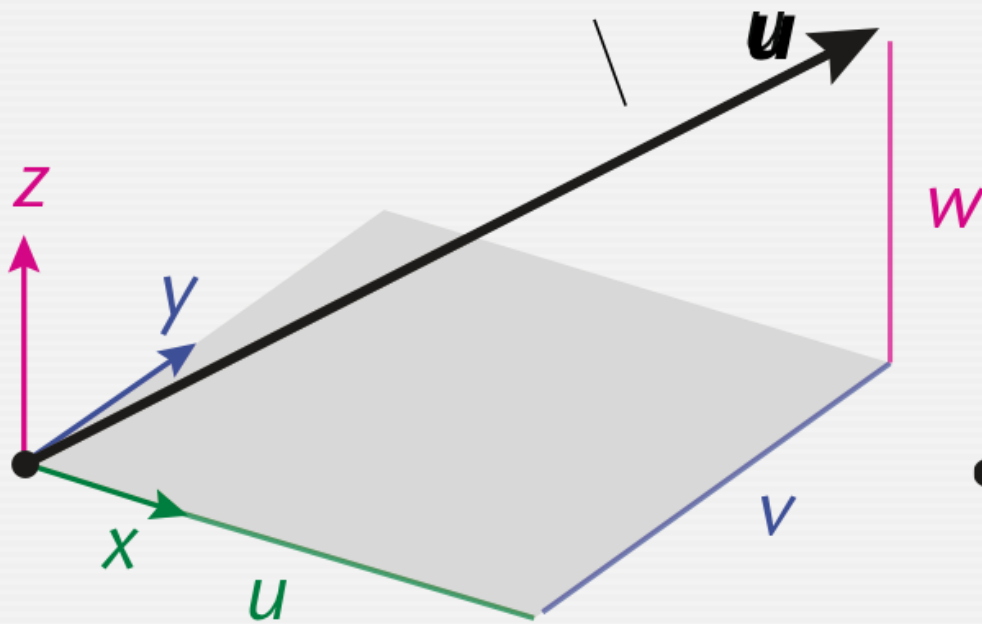
The **temporal average** of a time series  $a(t)$  measured at a point in space  $x_0$  is

$$\bar{a} = \frac{1}{N} \sum_{i=0}^{N-1} a(t_i, x_0) \quad a(t) = a'(t) + \bar{a} \quad \star$$

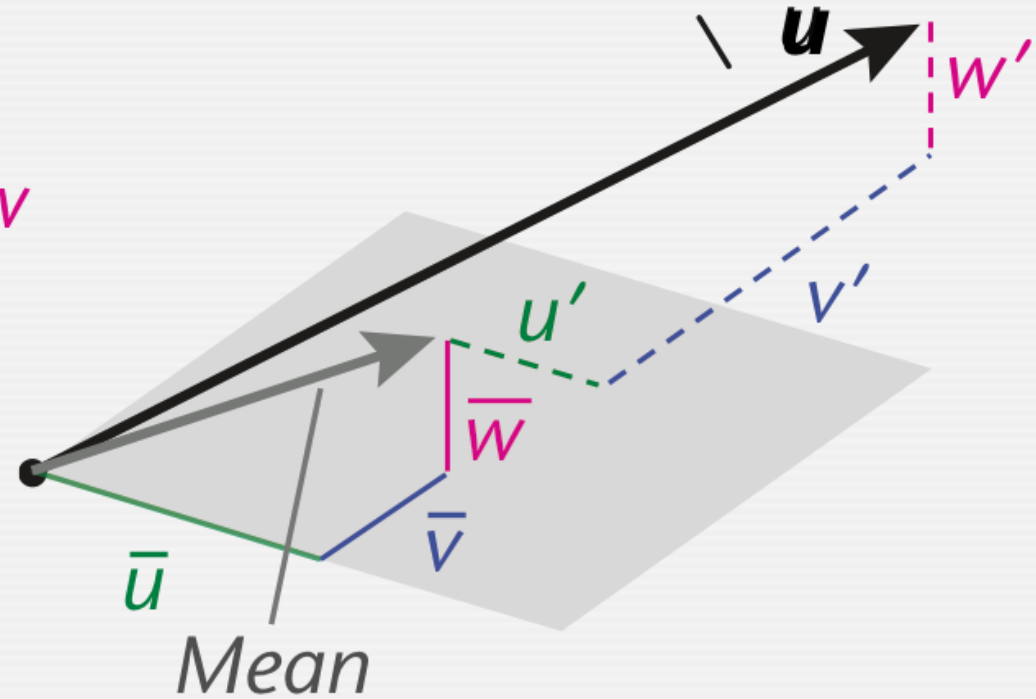


# Wind is a vector with components $u$ , $v$ , $w$

$$\mathbf{u} = \begin{bmatrix} u \\ v \\ w \end{bmatrix}$$



$$\mathbf{u} = \begin{bmatrix} \bar{u} + u' \\ \bar{v} + v' \\ \bar{w} + w' \end{bmatrix}$$



# Reynolds decomposition

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$$\overline{a'} = 0$$

By definition the average of all fluctuations must vanish.

$$\overline{(\bar{a} \times b')} = \bar{a} \times \overline{b'} = \square$$

$$\overline{(a)} = \overline{\bar{a} + a'} = \square$$

## Reynolds decomposition

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$$\overline{a'} = 0$$

By definition the average of all fluctuations must vanish.

$$\overline{(\bar{a} \times b')} = \bar{a} \times \overline{b'} = 0$$

$$\overline{(a)} = \overline{\bar{a} + a'} = \bar{a}$$

$$\overline{a \times b} = \overline{(\bar{a} + a') \times (\bar{b} + b')} = \boxed{\phantom{0}}$$

# Reynolds decomposition

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$$\overline{a'} = 0$$

By definition the average of all fluctuations must vanish.

$$\overline{(\bar{a} \times b')} = \bar{a} \times \overline{b'} = 0$$

$$\overline{(a)} = \overline{\bar{a} + a'} = \bar{a}$$

Covariance

$$\overline{a \times b} = \overline{(\bar{a} + a') \times (\bar{b} + b')} = \bar{a} \times \bar{b} + \overline{a'b'}$$

**We conclude:** A covariance is not necessarily vanishing. Covariances are often very important terms in turbulence.

# Integral statistics

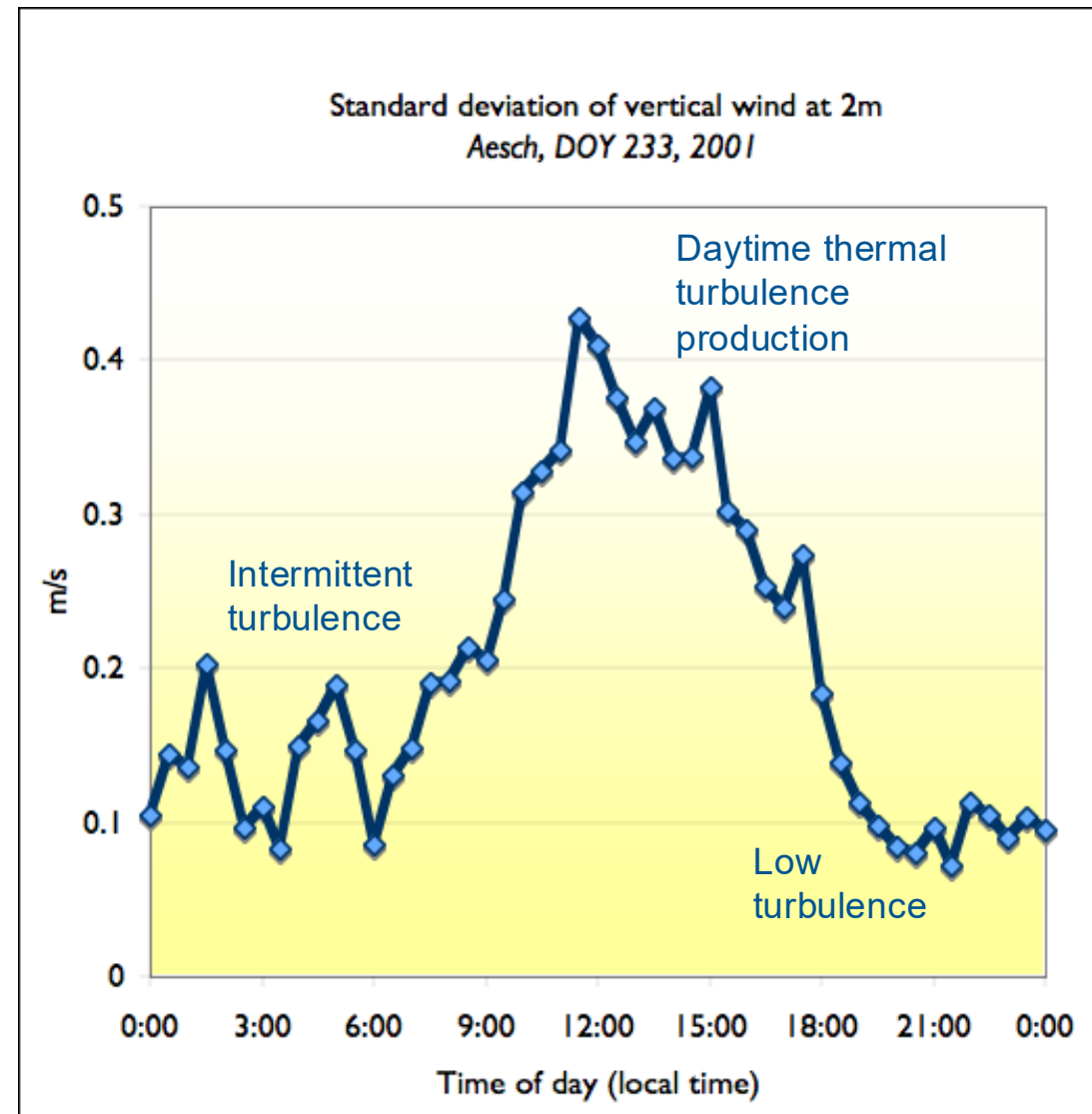
Also the **variance** of  $a$  in a turbulent time series is not zero.

It is defined by:

$$\overline{a'^2} = \frac{1}{N} \sum_{i=0}^{N-1} a'^2(t_i, x_0) \quad \star$$

Its square root is the **standard deviation** (same units as  $a$ )

$$\sigma_a = \sqrt{\overline{a'^2}} \quad \star$$



**Test your knowledge - During an hour, you measure air temperature  $T$  every 10 minutes according the table below. Calculate the following terms:**

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(a)  $\bar{T}$

(d)  $\overline{T'}$

(b)  $T'$  at 40 min

(e)  $\overline{T'^2}$

(c)  $T'^2$  at 20 min

(f)  $\overline{T'^2}$

Minutes	$T$
10	12.6°C
20	11.2°C
30	11.9°C
40	13.1°C
50	12.0°C
60	11.8°C

## Test your knowledge

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If  $\sigma_u = 0.4$  m/s,  $\sigma_v = 0.2$  m/s, and  $\sigma_w = 0.1$  m/s, calculate:

$$\overline{u'^2} + \overline{v'^2} + \overline{w'^2}$$

Hint:  $\sigma_a = \sqrt{\overline{a'^2}}$  ★

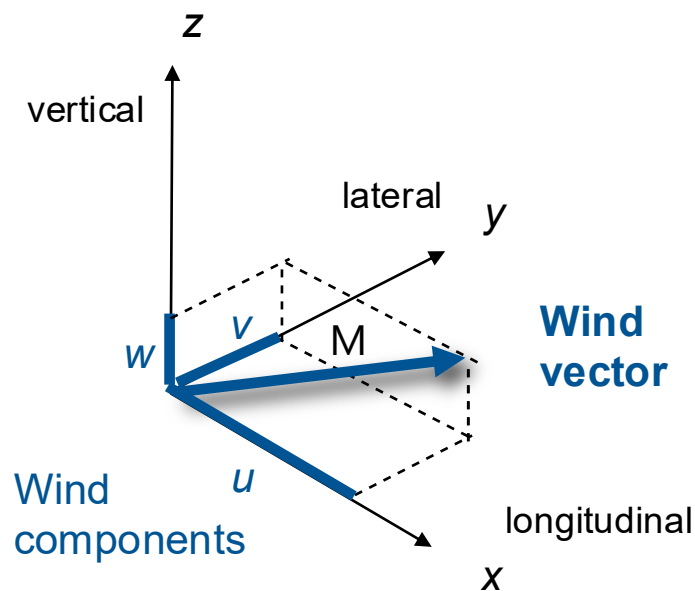
Join at:  
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# Integral statistics

**Turbulence intensities** are the dimensionless ratio between the standard deviation and the length of the mean wind vector  $M$ .



$$I_u = \sigma_u / M \quad \star$$

$$I_v = \sigma_v / M \quad \star$$

$$I_w = \sigma_w / M \quad \star$$

$$M = \sqrt{\overline{u^2} + \overline{v^2} + \overline{w^2}} \quad \star$$

## Turbulent kinetic energy

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Following the definition of kinetic energy ( $E=1/2 mv^2$ ) we can define a mean kinetic energy ( $MKE$ ) per unit mass  $m$  of the flow, namely

$$MKE/m = \frac{1}{2} (\bar{u}^2 + \bar{v}^2 + \bar{w}^2)$$

Similarly, the kinetic energy of the instantaneous deviations per unit mass ( $e$ ) is:

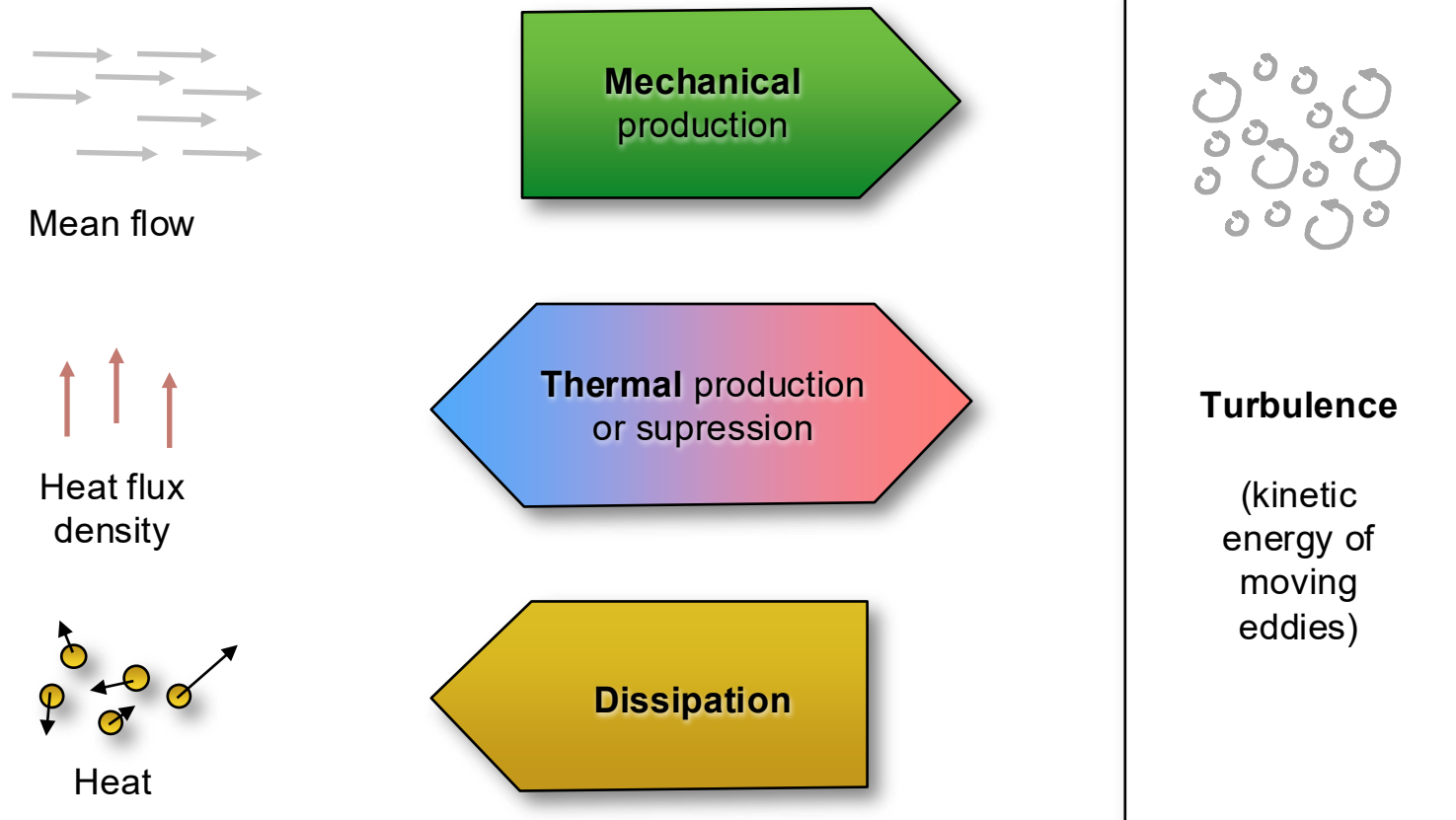
$$e = \frac{1}{2} (u'^2 + v'^2 + w'^2)$$

The average  $e$  is called mean **turbulent kinetic energy** (TKE):

$$\bar{e} = \frac{1}{2} (\overline{u'^2} + \overline{v'^2} + \overline{w'^2}) \quad \star$$

# The TKE budget

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## TKE in the boundary layer

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- TKE increases with \_\_\_\_\_ wind speed.  
(increasing or decreasing?)
- TKE is greater over \_\_\_\_\_ than \_\_\_\_\_ surfaces  
(rough / smooth)
- TKE is greatest in \_\_\_\_\_, least in \_\_\_\_\_ atmosphere.  
(stable / unstable)
- In most cases, the vertical turbulent energy (and therefore the vertical turbulence intensity) is smaller compared to the horizontal fluctuations.

## TKE in the boundary layer

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- TKE increases with increasing wind speed.
- TKE is greater over rough than smooth surfaces.
- TKE is greatest in unstable, least in stable air

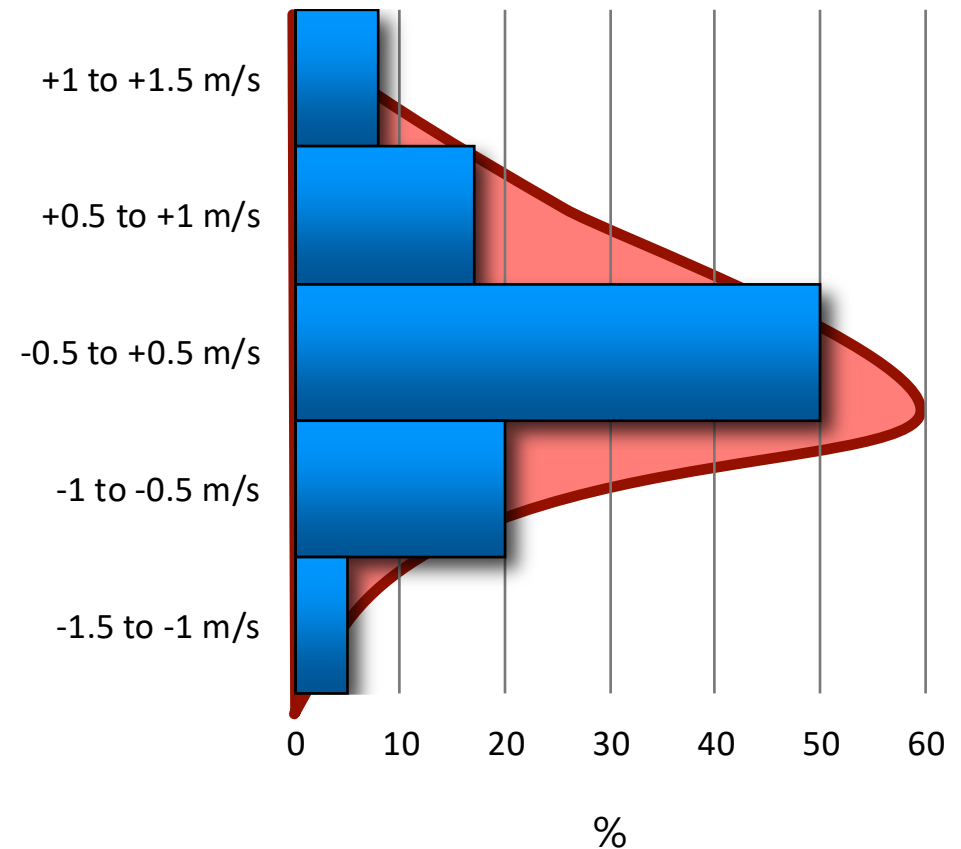
# Probability densities.

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A **probability density function** describes the probability of occurrence of a particular value of any parameter.

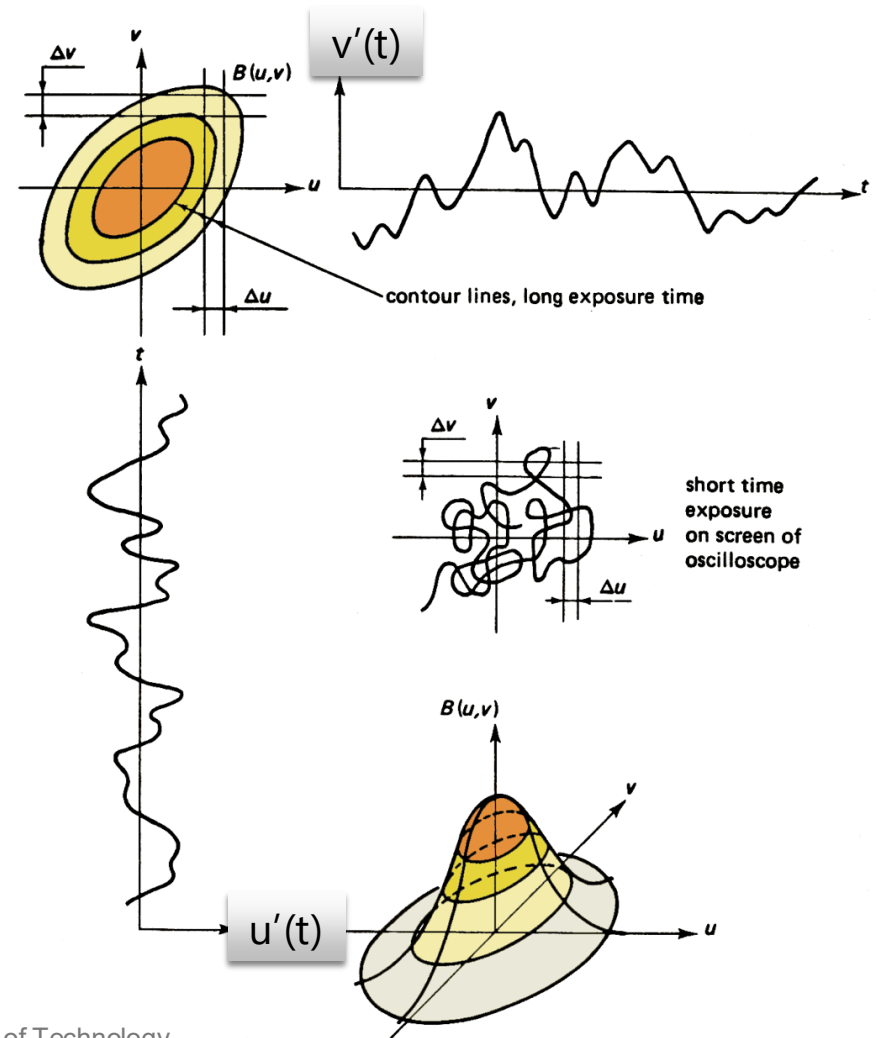
It is useful to look at the probability density functions of turbulent fluctuations ( $u', v', w', p', T', q'$ ).

A **histogram** is a discrete representation of a probability density.



# Joint probability density

A two (or higher) dimensional probability density of co-occurrence of two (or more) variables is called joint probability density.



H. Tennekes and J. L. Lumley (1972): A first course in turbulence. Massachusetts Institute of Technology.

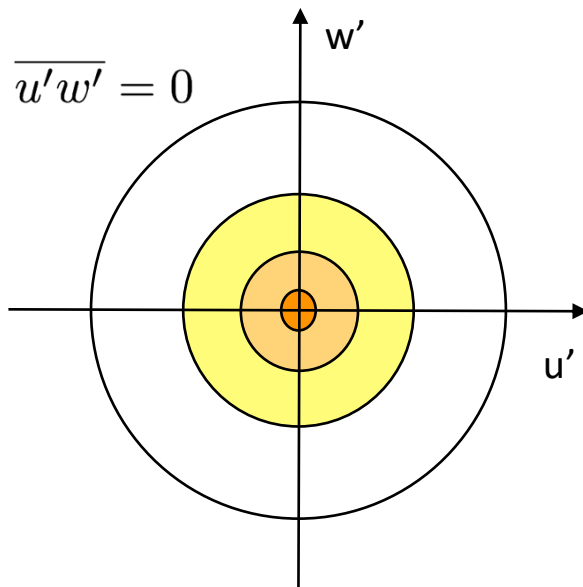
# Correlation coefficient

Covariance

$$r_{uw} = \frac{\overline{u'w'}}{\sigma_u \sigma_w} \quad \star$$

Standard deviation

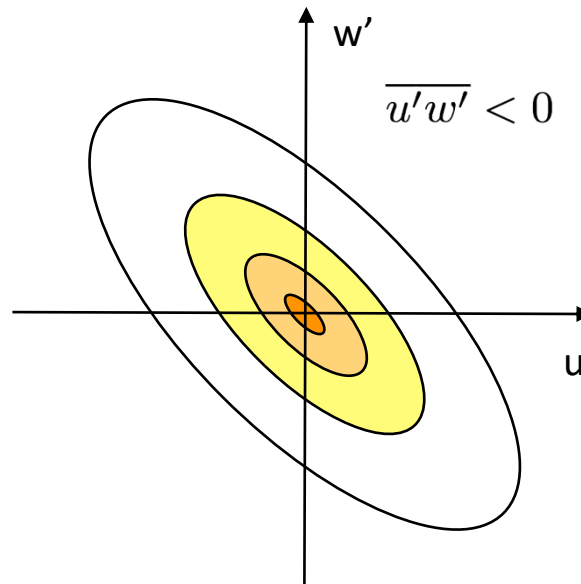
no correlation



$$\overline{u'w'} = 0$$

$$r_{uw} = 0$$

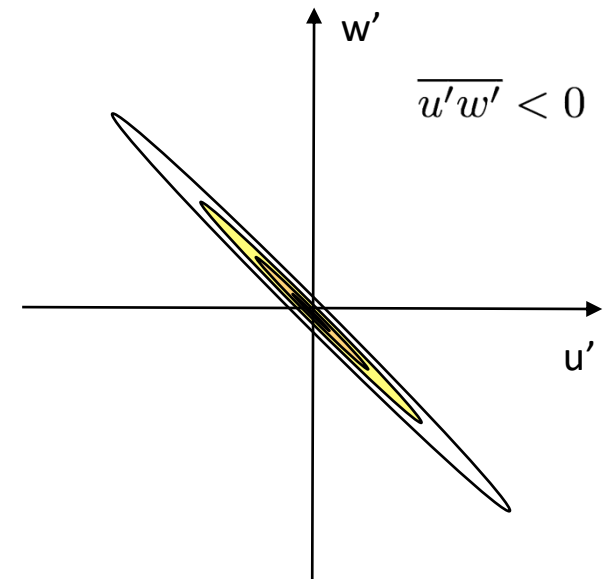
moderate correlation



$$\overline{u'w'} < 0$$

$$0 > r_{uw} > -1$$

nearly perfect correlation



$$\overline{u'w'} < 0$$

$$r_{uw} \approx -1$$

## Take home points

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- **Reynolds decomposition** allows to separate the mean from the turbulent part of a time series.
- We are rarely interested in the instantaneous values of the turbulent part - but only in the **integral effects**.
- We can use **probability distributions** to predict exchange efficiency and mixing in a turbulent flow.